

Figure 1: ATA 42 antenna array at Hat Creek

REAL TIME IMAGING. Melvyn Wright - CASPER workshop Aug 2010

- Preaching to the choir
 - Goals and Implementation

- Preaching to the unconverted
 - Science and Sociology

MOTIVATION

- Astronomers primarily interested in astronomy.
 - data reduction preoccupies radio astronomy specialists.
 - ALMA & SKA should be easily used by non specialists.
- Old paradigm: custom DSP + off-line calibration & imaging.
 - mismatch between on-line and off-line processing bandwidths
 - off-line can handle only a few percent of data rates from DSP.
 - data processing problems for large-N arrays.

- PROBLEMS -

- Data reduction & analysis bottleneck. Large time before analysis.
- User expertise with aperture synthesis data.
- RFI, bad data, flagging & editing.
- Background & confusing source subtraction
- High data rates.
- Lost science opportunities without real time feedback.

SOLUTIONS

- Heterogeneous DSP: FPGA, GPU & clusters for flexible programming.
- Image large FOV with high frequency and time resolution.
- Simultaneously image: science targets, calibrators & confusing sources.
- Variable sources and RFI handled in real time.
- Real time feedback into imaging and deconvolution.

SKA SCIENCE REQUIREMENTS

- simultaneous images of multiple regions in the FoV.
- Image fidelity 10^4 between 0.5 and 25 GHz.
- Bandwidth ~ 4 GHz (25% below 16 GHz).
- 10^5 spectral channels per band.
- accumulation interval ~ 0.5 s.
- 10^5 beam areas at maximum angular resolution.

- DATA PROCESSING MODEL -

- Calibration and editing in close to real time using a sky model.
- Calibration parameters fed back into imagers and beam formers.
- Subtract sky model from uv data before imaging.
- Observations update and improve the a-priori model.
- Sky model is final calibrated image when observations are complete.

WIDE FIELD IMAGING

- For high dynamic range need to subtract strong sources outside regions of interest, including sidelobes of primary beam.
- Antenna station beam pattern is time variable.
- Deconvolving large FOV is very expensive off-line
- Sky model used to calibrate uv data & subtract confusing sources.

SYSTEM DESIGN FEATURES

- Multiple delay & phase centers for targets over a wide FOV.
- High performance DSP handle high data rates in parallel.
- RFI mitigation with high time and frequency resolution.
- Calibration and feedback into beam formers in real time.
- Image & deconvolve in close to real time.

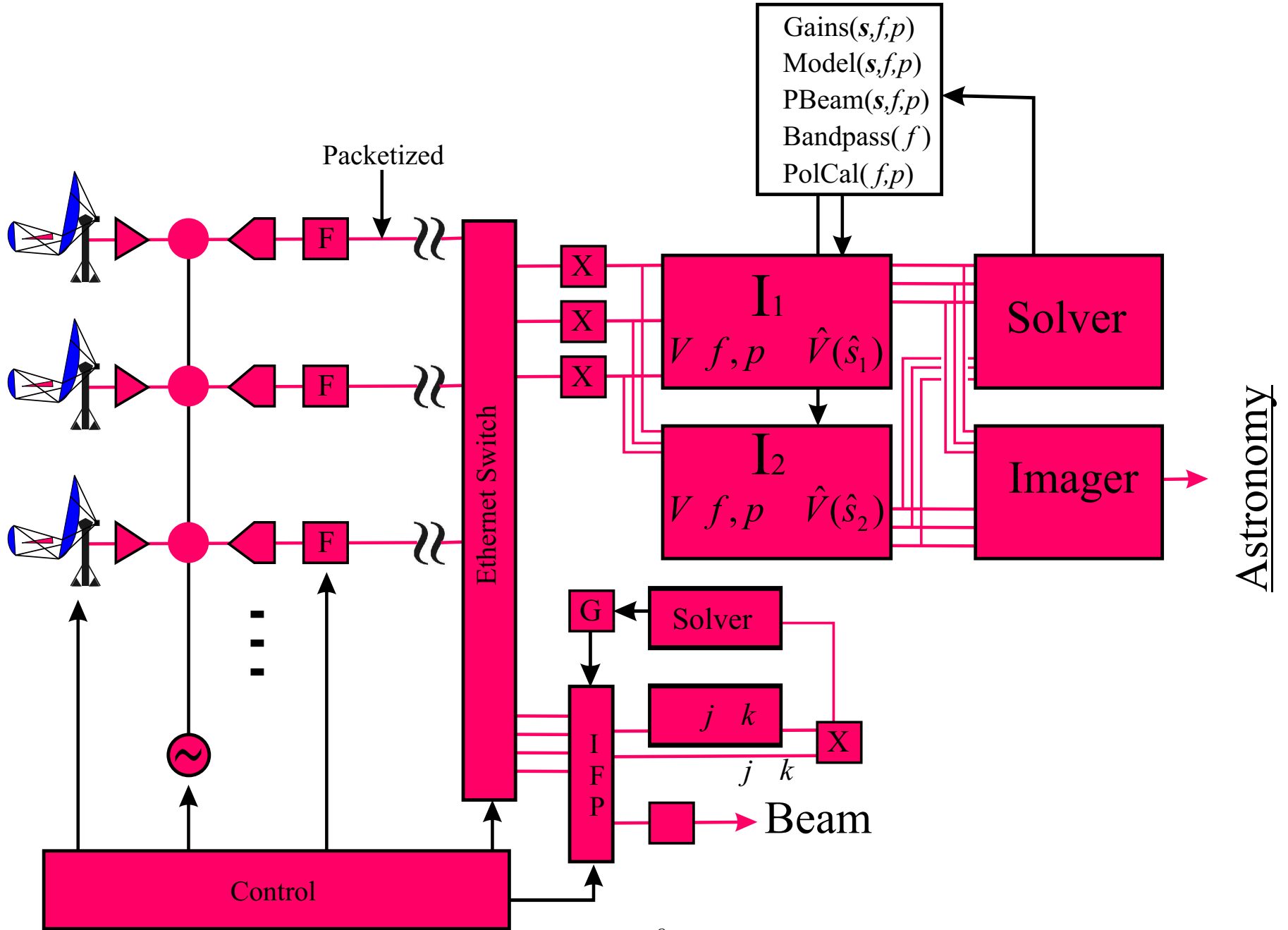


Figure 2: Data flow from telescopes to images

— SYSTEM ARCHITECTURE —

- Hierarchical beam formation & correlators image large FOV.
- Phased array beams can be formed anywhere in the sky.
- Station beam depends on array geometry, source direction & complex antenna weight.
- Correlators image multiple regions in a large FOV.
- Beam formers channel collecting area into expensive back ends.

DIGITIZE & PACKETIZE

- Total bandwidth $N_{ant} \times B \times N_{pol}$.
 - digitize & packetize using COTS hardware and protocols.
- Data bandwidth $N_{ant} \times 2B \times N_{pol} \times N_{bits}$,
 $4 \times 10^{12} (N_{ant}/1000) (B/GHz) (N_{pol}/2)$ bytes/s
using 8-bit digitization.

PARALLEL PROCESSING - CHANNELIZE

- Spectral resolution, RFI rejection, multifrequency synthesis (MFS).
- Science & RFI require large N_{chan} — favors FX architecture.
 - polyphase filter isolates frequency channels. e.g. RFI.
- Data bandwidth $N_{ant} \times 2B/N_{chan} \times N_{chan} \times N_{pol} \times N_{bits}$.
 - reduce bit width after RFI rejection
- Parallel processing reduces data rate by N_{chan}

ADVANTAGES OF USING SWITCHES

- COTS rather than custom backplanes for large N_{ant} .
- Packets can be routed to multiple asynchronous DSP engines.
- Include metadata needed to calibrate & image multiple regions.
- Flexible routing to beam formers & correlators.
- DSP can be upgraded & reprogrammed with minimum interruption.

- CORRELATORS -

- Data bandwidth from correlator for full FOV:

$$N_{ant}(N_{ant} + 1)/2 \times N_{pol} \times N_{chan} \times N_{bits} \times 2 \text{ sdot} \times D_{max}/\lambda$$
$$\sim 10^8 (N_{ant}/1000)^2 (N_{pol}/4) (D_{max}/km) (\lambda/cm)^{-1} \text{ bytes/s}$$

using 2×16 bits per complex channel.

————— INTEGRATE AT MULTIPLE PHASE CENTERS —————

- Average to reduce data rate and FOV at each phase center.
- Data bandwidth for antenna primary beam is:

$$N_{ant}(N_{ant} - 1)/2 \times N_{pol} \times N_{chan} \times N_{bits} \times 2 \text{ sdot} \times D_{max}/D_{ant}$$
$$\sim 10^5 (N_{ant}/1000)^2 (N_{pol}/4) (D_{max}/km) (D_{ant}/12m)^{-1} \text{ bytes/s.}$$

using 2×16 bits per complex channel.

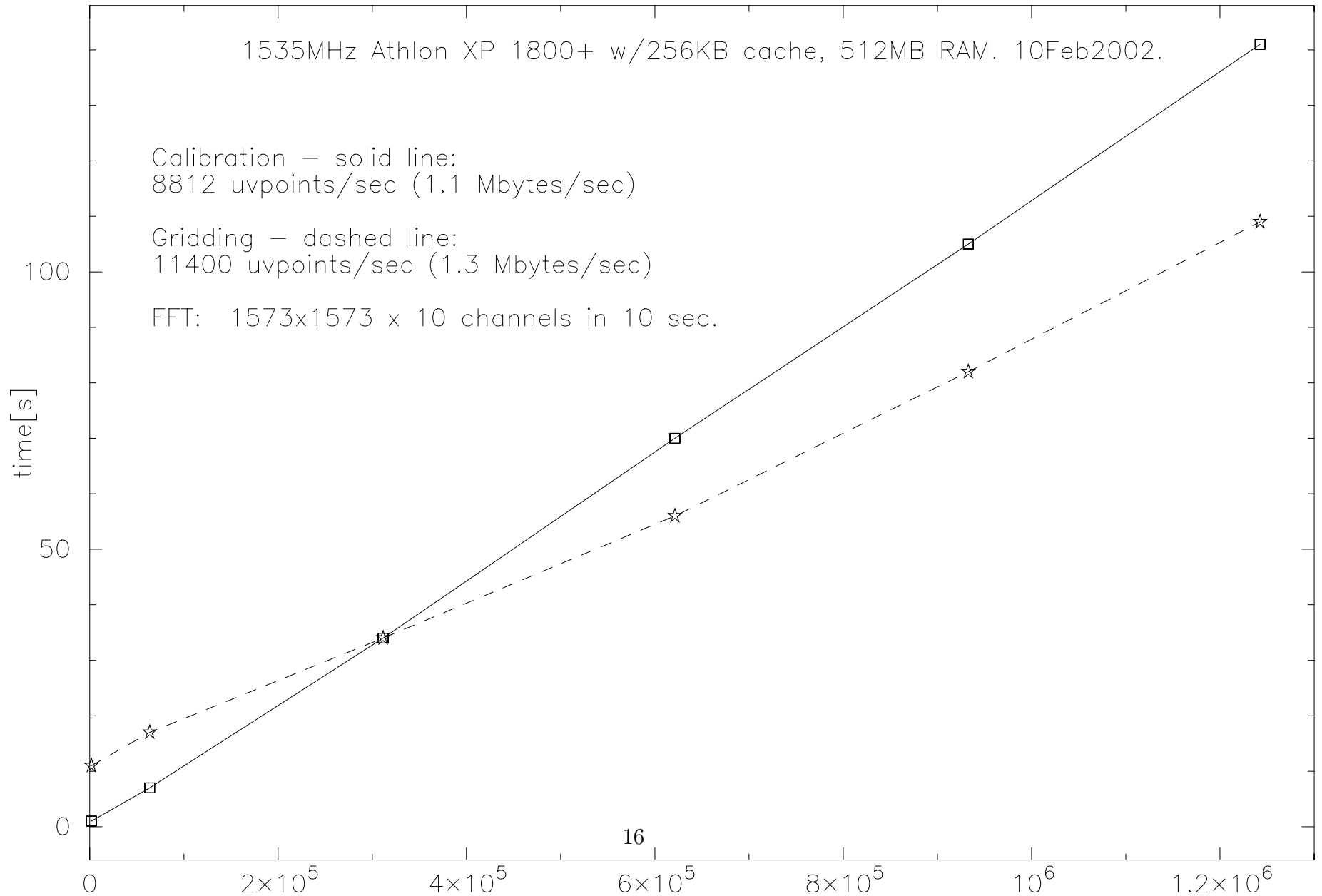
MIRIAD Timings for 1573x1573x10 channel Imaging
(simulated ALMA data with 60 antennas in 4 km configuration)

1535MHz Athlon XP 1800+ w/256KB cache, 512MB RAM. 10Feb2002.

Calibration – solid line:
8812 uvpoints/sec (1.1 Mbytes/sec)

Gridding – dashed line:
11400 uvpoints/sec (1.3 Mbytes/sec)

FFT: 1573x1573 x 10 channels in 10 sec.



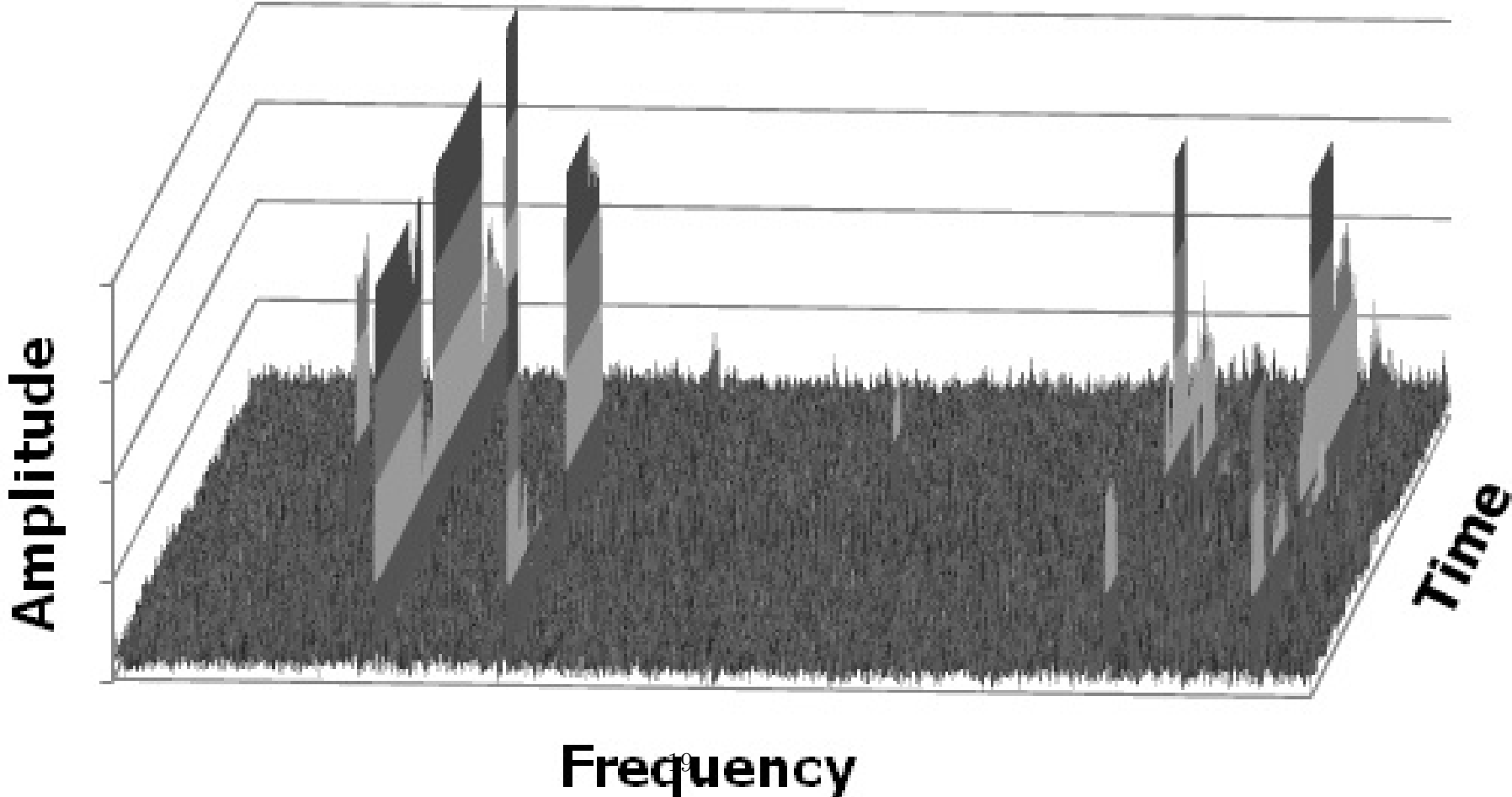
- CALIBRATION -

- Station Beam, Gain, Bandpass, & Polarization.
 - primary beam is complex product of station voltage patterns.
 - time variable PB, pointing & atmospheric fluctuations.
- Non isoplanicity – calibrate the data for each phase center.
- Image science targets, calibrators, & confusing sources.
 - identify confusing sources from a-priori images.

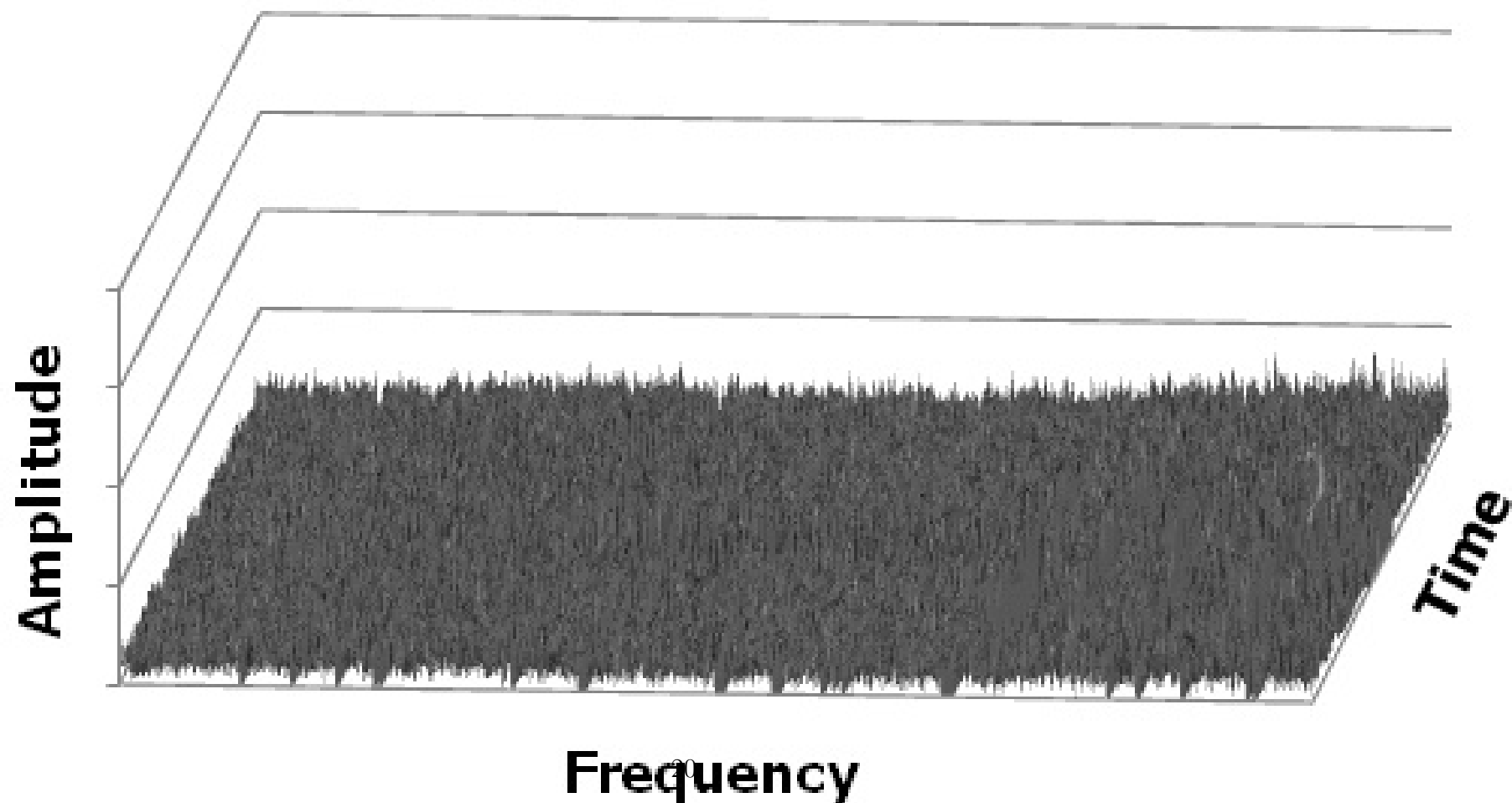
RFI MITIGATION

- Subtract RFI before averaging in time and frequency.
 - Gaussian filtering: MAD, Spectral Kurtosis
- Characterize RFI as a function of time, frequency and polarization.
 - SNR improved by pointing some antennas at RFI sources.
 - may need fast sampled uv data (e.g. satellites)
- Null formation by controlling station beam.

Pre-flagged Data



Post-flagged Data



Nulling WAAS on Galaxy 15

1 part in 10^8 of transmission

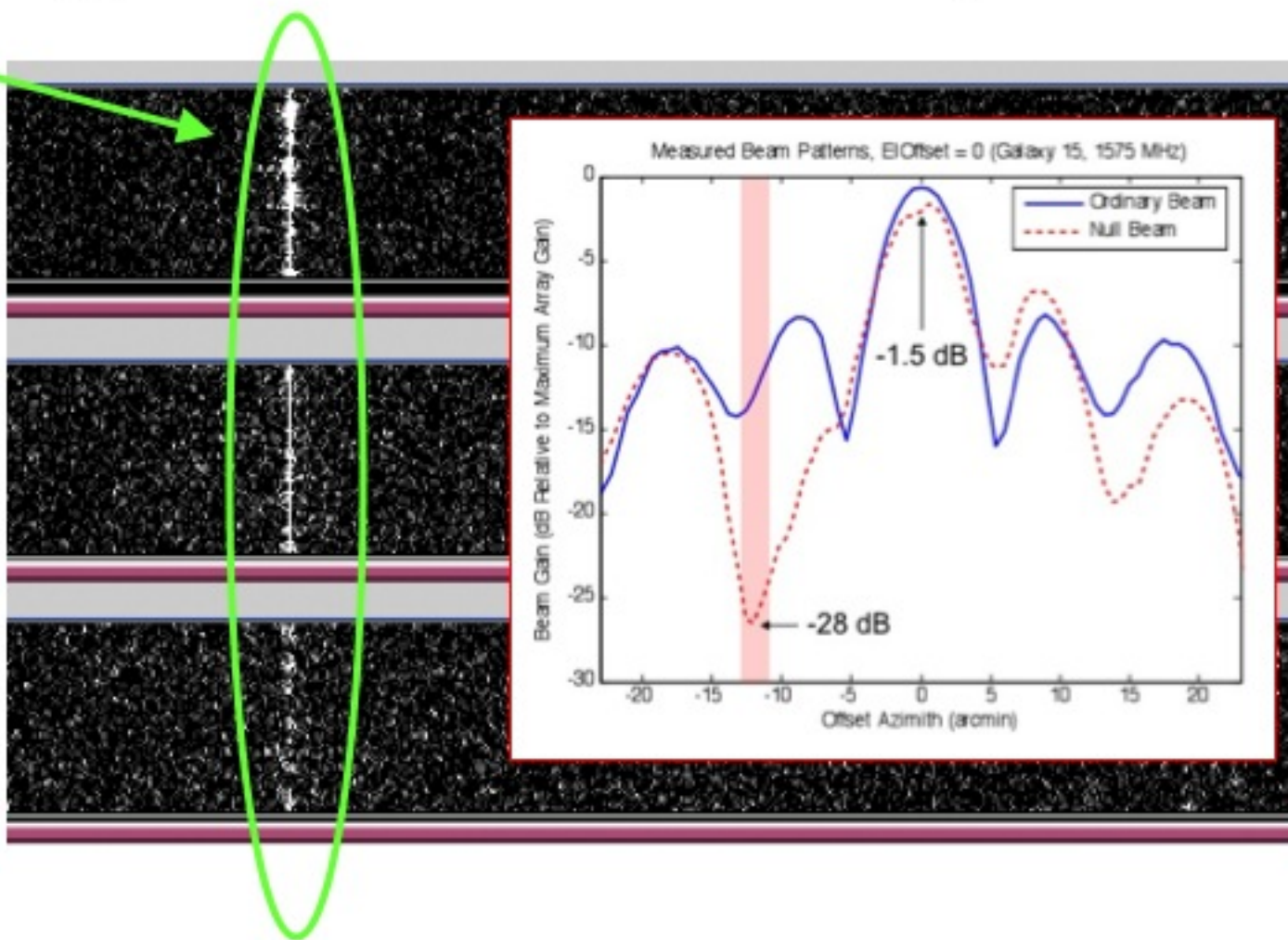
On-Axis:

Off-Axis:

10dB down

Nullled:

28dB down



IMAGING

- Image parallel uv data streams with a-priori model subtracted.
 - difference images update the model & improve calibration.
- Deconvolve by subtracting model & sidelobes of confusing sources.
 - stop when model image is consistent with uv data streams.
- Transient source are inconsistent with the model. Save this uv data.
 - make and keep χ^2 image to identify transient & RFI sources.

- USER INTERFACE -

- Imaging is a dynamic process.
 - look at convergence of sky model and χ^2 image.
- Phase centers can be moved for science goals, or better calibration.
 - new sources are discovered in the imaging process.
 - isoplanatic patches may vary during observations
 - calibration across the FoV.

- ARCHIVE -

- High bandwidth archive is an integral part of real-time system.
 - save uv data streams with metadata.
 - uv data can be replayed through imaging system.
- Better sky model used to improve calibration.
- Save transient source data for further analysis.

CONCLUSION

- Delayed calibration & analysis limit the science which can be done.
- Reduce burden of data reduction on users.
 - expertise which many users do not have.
- Make best use of both telescope and human resources.